



Royal Netherlands  
Meteorological Institute  
Ministry of Infrastructure  
and Water Management

# Review of Equivalent Neutral Winds and Stress Equivalent Winds

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# Why Calibrate to 'Winds' Rather than Stress



- Radar backscatter was observed to be dependent on wind speed and/or wave height in the 1950s.
- In 1963 Dick Moore had the idea that backscatter could be used to estimate oceanic variables.
- The NASA Sea Surface Stress ( $S^3$ ) report indicated that scatterometers probably did respond to stress rather than wind.
- The number of stress observations available for calibration was approximately zero. Therefore, it was desirable to calibrate to wind, for which the collocated observations would be plentiful.
- Willard Pierson, Vince Cardone and colleagues found that wind speed could be adjusted to be more consistent with surface stress.
  - Equivalent neutral wind
  - But there was a questionable assumption which brings us to stress equivalent winds



# Qualitative Description of **Earth-Relative Winds** and **Equivalent Neutral Winds** and **Stress Equivalent Winds**

- **Earth relative winds** are wind speeds measured relative to the ‘fixed’ earth
  - **Earth relative winds** are the standard for almost all atmospheric applications:
    - Operational meteorology (forecasts and analyses)
    - Hurricane and marine cyclone analyses
  - Most meteorologists think in terms of **earth relative winds**
- **Equivalent neutral winds** are used to determine (or as a proxy for) surface turbulent stress.
  - They have been designed for very simple conversion to stress.
    - They assume an average (of some sort) air density, which causes systematic errors when converting from a stress to a wind and a friction velocity
      - Air density is about  $1.1 \text{ kg m}^{-3}$  in the tropics outside of strong cyclones
      - Air density can be  $1.4 \text{ kg m}^{-3}$  in the in extremely cold air outside of strong cyclones
- **Stress Equivalent winds** correct for this problem, defining a satellite wind speed that does take account of the local air density
  - Which implies that for comparison air density must be used to determine **stress-equivalent winds**



# Stress – Parameterization with a Drag Coefficient

- The surface turbulent stress (momentum flux density) is usually parameterized as

$$\tau = \rho C_D U_{10}^2$$

- This form can be more accurately written as

$$\boldsymbol{\tau} = \rho C_D |\mathbf{U}_{10}| \mathbf{U}_{10}$$

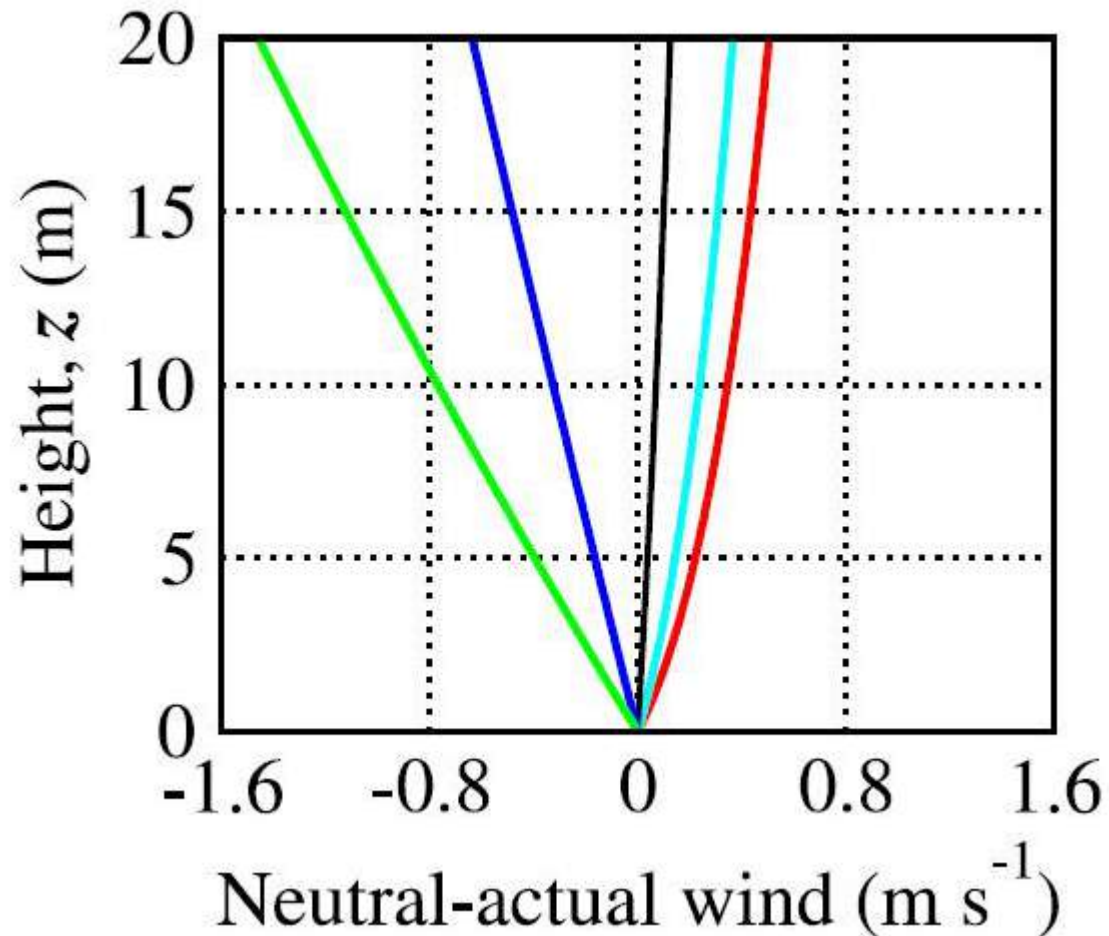
- It can be further improved in terms of surface relative wind vectors:

$$\boldsymbol{\tau} = \rho C_D |\mathbf{U}_{10} - \mathbf{U}_{sfc}| (\mathbf{U}_{10} - \mathbf{U}_{sfc})$$

- Does a scatterometer respond to  $\mathbf{U}_{10}$  or to  $\mathbf{U}_{10} - \mathbf{U}_{sfc}$ ?
  - *Cornillon and Park* (2001, *GRL*), *Kelly et al.* (2001, *GRL*), and *Chelton et al.* (2004, *Science*) showed that scatterometer winds were relative to surface currents.
  - *Bentamy et al.* (2001, *JTech*) indicate there is also a dependence on wave characteristics.
  - *Bourassa* (2006, *WIT Press*) showed that wave dependency can be parameterized as a change in  $\mathbf{U}_{sfc}$  for wind and waves moving in the same direction.
  - Hence, empirical GMFs tuned to  $\mathbf{U}_{sfc}$  incorporate wave (motion) dependency *Portabella et al.* (2009, *JAOT*)



# Equivalent Neutral wind speed minus Earth Relative wind speed for $U_{10} = 6 \text{ ms}^{-1}$



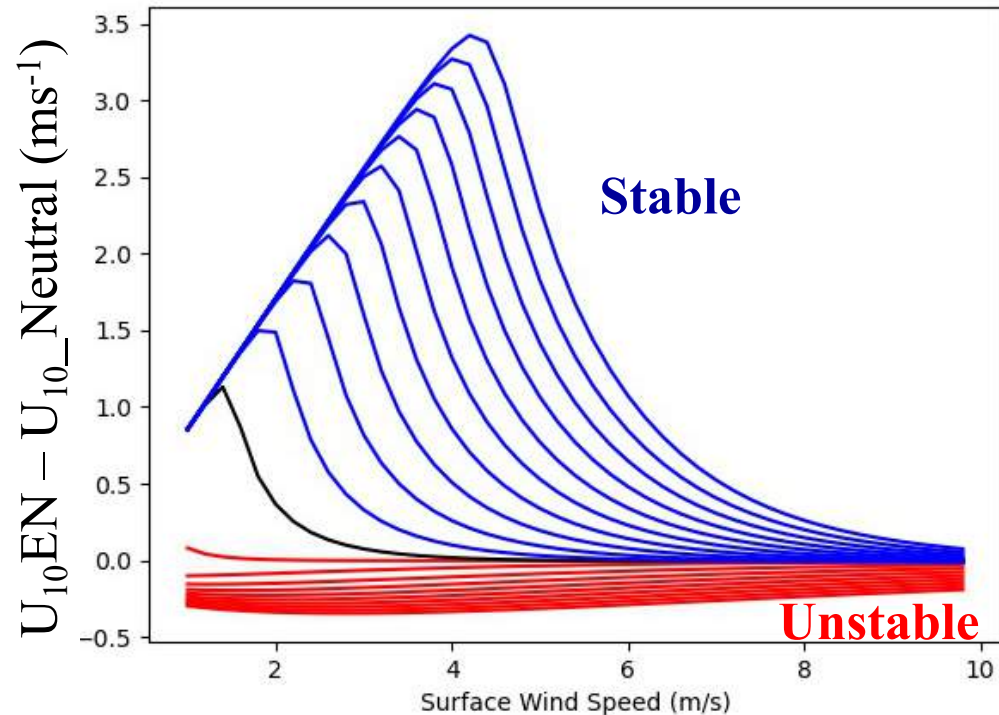
- For equal and opposite air/sea temperature differences, the change is greater for the stable conditions

- These results require a roughness length that is dependent on friction velocity. Otherwise, it can change a lot

# How To Calculate Equivalent Neutral Winds & Common Errors

- **Correct Approach**
- **Calculate the friction velocity (or stress)**
  - **accounting for atmospheric boundary-layer stability, and**
  - **And using a stress depending roughness length.**
- **Use these friction velocity and roughness length to determine a wind speed at 10 m height ( $z=10$ ) with zero additional impact from atmospheric stability.**

- **Common errors: #1 Neutral winds**



- **#2 Kara et al. (200xx) found that application of a constant roughness length or a roughness length without a dependency on stress (a Charnock like roughness length results in systematic errors in equivalent neutral winds**



# What If Scatterometers Respond to Stress?

- If scatterometers respond in a manner consistent with **equivalent neutral winds**, then they respond to changes in friction velocity ( $u_*$ ).

$$U_{10EN} = \frac{u_*}{k} \ln \left( \frac{10}{z_o} \right)$$

$$U_{10EN} = \frac{(\tau / \rho)^{0.5}}{k} \ln(10 / z_o)$$

- $\tau = \rho_{air} u_*^2$
- Replace  $u_*$  in the traditional definition of equivalent neutral winds – write in terms of  $\tau$

- If scatterometers respond to stress, then it responds to changes in air density and change in friction velocity!
- If scatterometers respond to stress, then calibrations to **stress equivalent winds** will not depend on actual air mass density (*de Kloe et al.*, 2017, *JSTARS*)

$$\vec{u}_{10s} = \vec{u}_{10n} \sqrt{\frac{\rho_{air}}{\langle \rho_{air} \rangle}}$$

$$U_{10S} = \frac{(\tau / \langle \rho \rangle)^{0.5}}{k} \ln(10 / z_o)$$





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