



Evaluation of COWVR as a Cost-Effective Sensor for Ocean Vector Winds and Other Air-Sea Variables

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Outline

- I. What is COWVR
 - A. The Basics
 - B. Advantages
 - C. Risks
- II. What does RSS plan to do with it?
 - A. Adapt the WindSat Analysis Package to COWVR
 - B. Evaluate COWVR wind vectors relative to WindSat, Scatterometers and moored buoys.
 - C. Evaluate COWVR wind speed relative to conventional radiometers



COWVR (Compact Ocean Wind Vector Radiometer)

PI – Shannon Brown, JPL

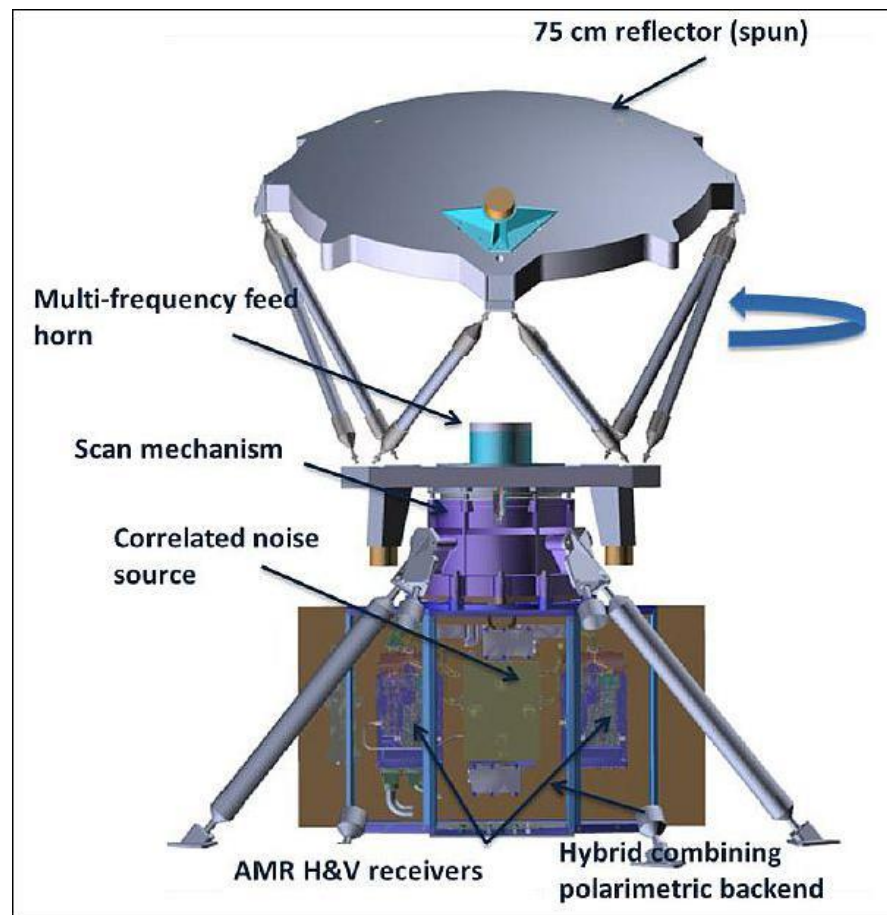
Funder – US Air Force

Fully Polarimetric Radiometer at 18.7, 23.8 and 33.9 GHz

Single feed horn for all 3 frequencies

Only the reflector rotates – the receiver is fixed to the spacecraft – No BAPTA – spinning angular momentum almost 50 times less than WindSat

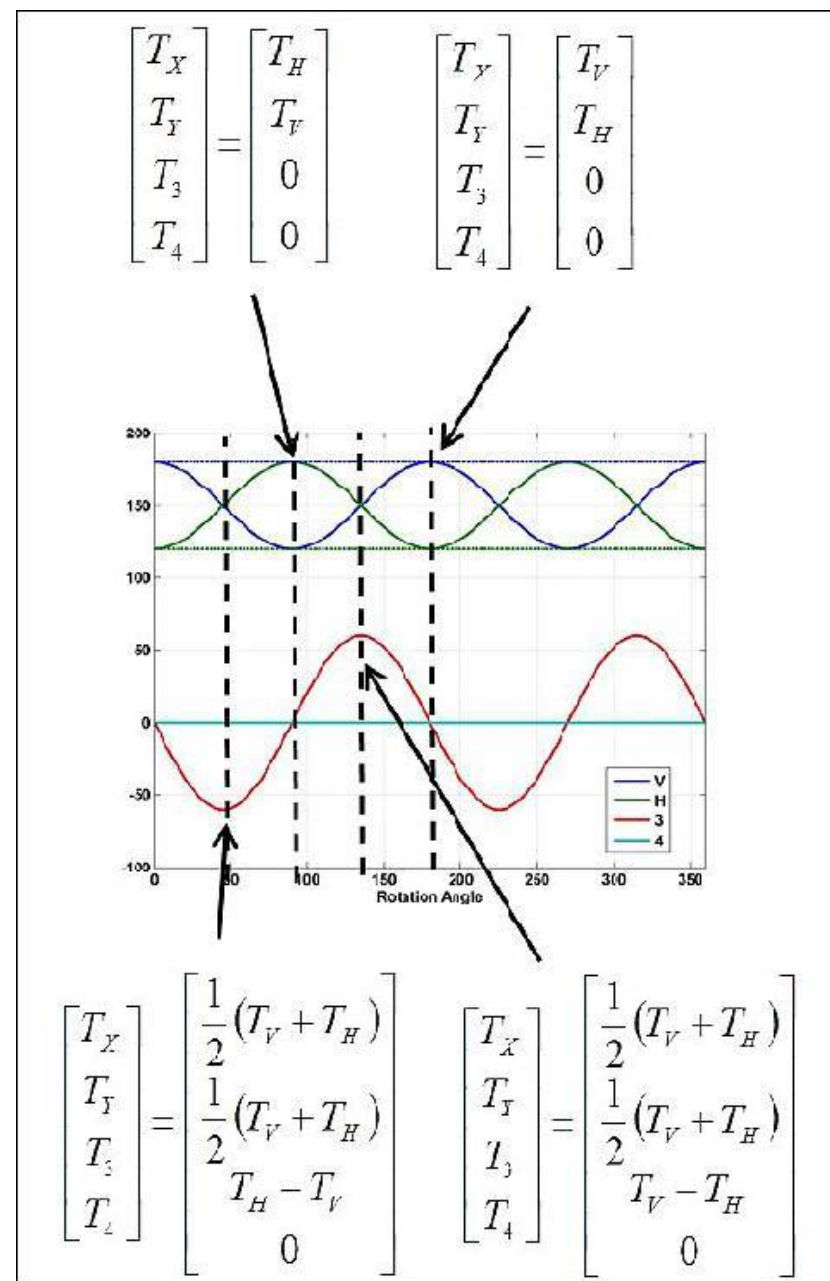
No External Calibration Loads -- Internally Calibrated Using PIN Diodes and correlated noise sources.



Implications of these features:

1. Polarizations are mixed as the reflector rotates

- But receiver is fully polarimetric, which allows the polarization state to be deduced even when basis is rotated.
- Technology has been demonstrated in the lab and for airborne radiometers.
- Requires a close match for the antenna patterns for the various components of the Stokes vector (or at least, a detailed understanding of the differences).

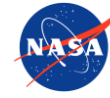




Implications of these features:

2. Lack of External Calibration Targets Allows for an Almost Uninterrupted 360 degree scan.

- Each location is observed twice at different azimuth angles.
- This is very good!
- WindSat had such “2-look” capability for part of the scan.
- RSS and others have shown that wind vectors are substantially improved by 2 looks.



Implications of these features:

3. **Internal calibration sources can be tricky.**
 - Radiance may vary slowly over time due to changes in source or PIN diode switches.
 - Need to use innovative cal-val methods to ensure that any such drifts are characterized and removed.
 - Aquarius, SMAP and GMI* all use internal calibration sources.
 - Aquarius had drifts issues, but SMAP is much improved.

*GMI has traditional calibration targets too.



Launch + Launch Vehicle

- Launch was scheduled for July 2018 but is now delayed until ????

Original Launch Plan.

- “Commercial Rideshare” launch shared with numerous other, mostly smaller satellites
- COWVR project doesn’t get to choose the exact orbit or launch window, but....
- The approach leads to substantial cost savings (25% to 50%) relative to a dedicated launch vehicle.



RSS Activities Related to COWVR

- Pre-launch Simulations
- Geolocation
- Footprint Resampling
- Calibration
- Vector Wind Algorithm
- Vapor, Cloud and Rain Algorithm

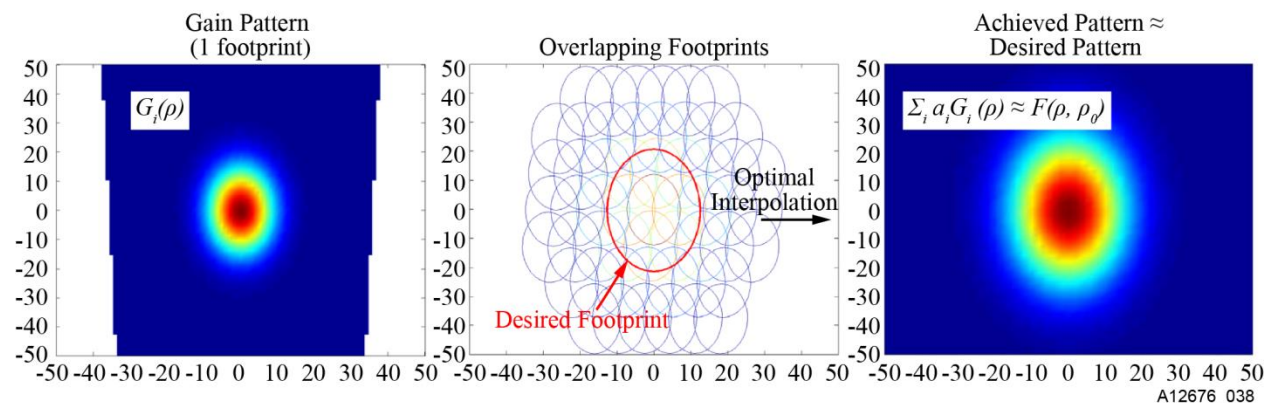


Prelaunch Simulation

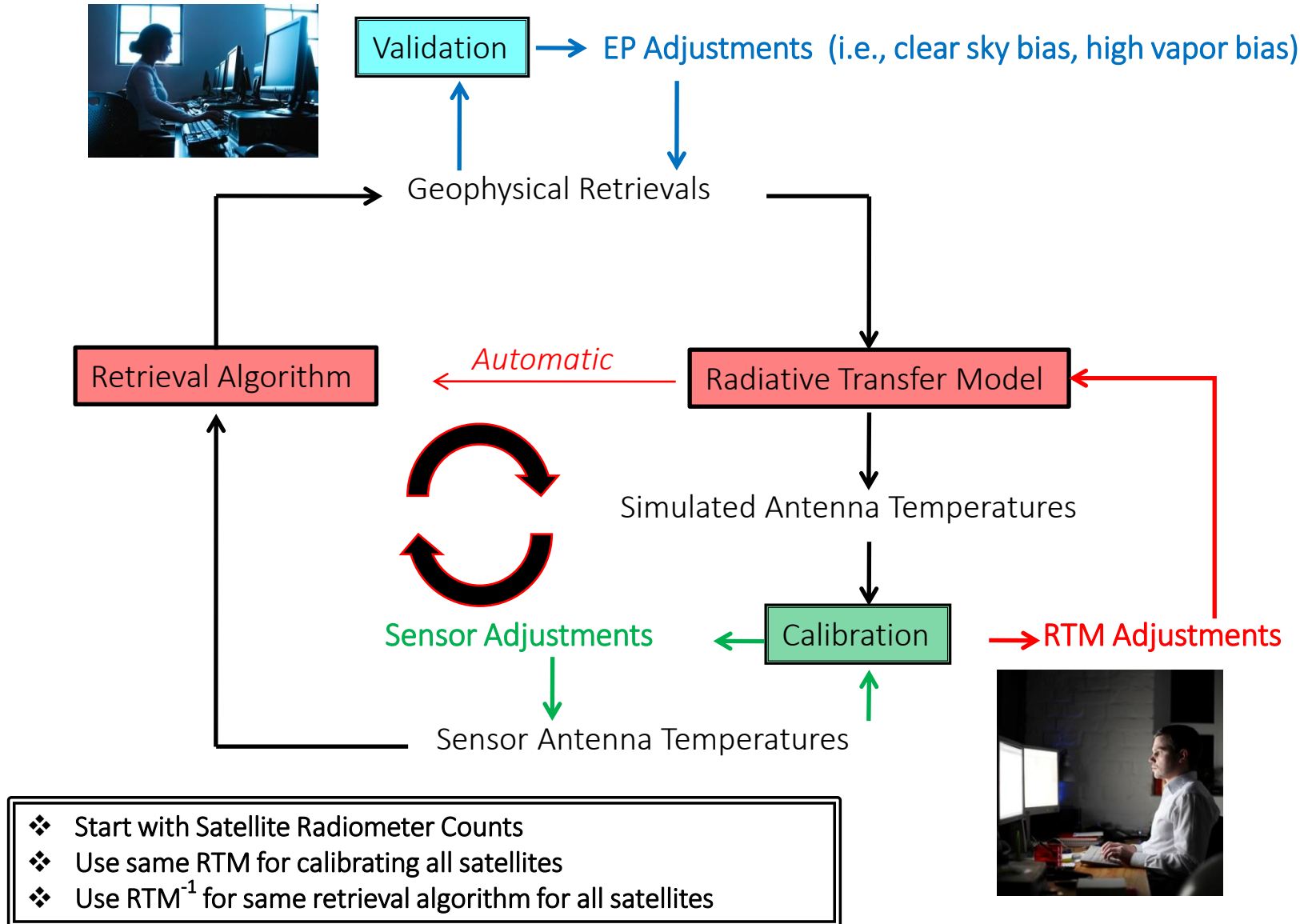
- End-to-End Satellite Simulator
 - Environmental Conditions for NWP output
 - Wind, SST, Salinity, Profiles of Temperature, Vapor, Clouds and Rain + Total electron content in the ionosphere.
 - RTM used to calculate top-of-the-atmosphere T_b
 - T_b converted to T_A using antenna spill-over, cross-pol and geometrical polarization rotation.
 - Noise is added to T_A to account for receiver noise
- Simulated T_A is then used to develop and test retrieval algorithms
- Results from retrievals can be compared to known conditions at the input to evaluate algorithm performance.

Geolocation and Resampling

- Geolocation
 - Satellite Location and Attitude used to compute footprint location on ground, as well as incidence angle, sun location, etc.
 - For real COWVR data, the locations of coastlines and similar features can be used to evaluate. Often Antenna Boresights need to be adjusted by a few 10ths of a degree. This can depend on the polarization under study.
- Footprint Resampling to Common Footprint
 - Optimum interpolation



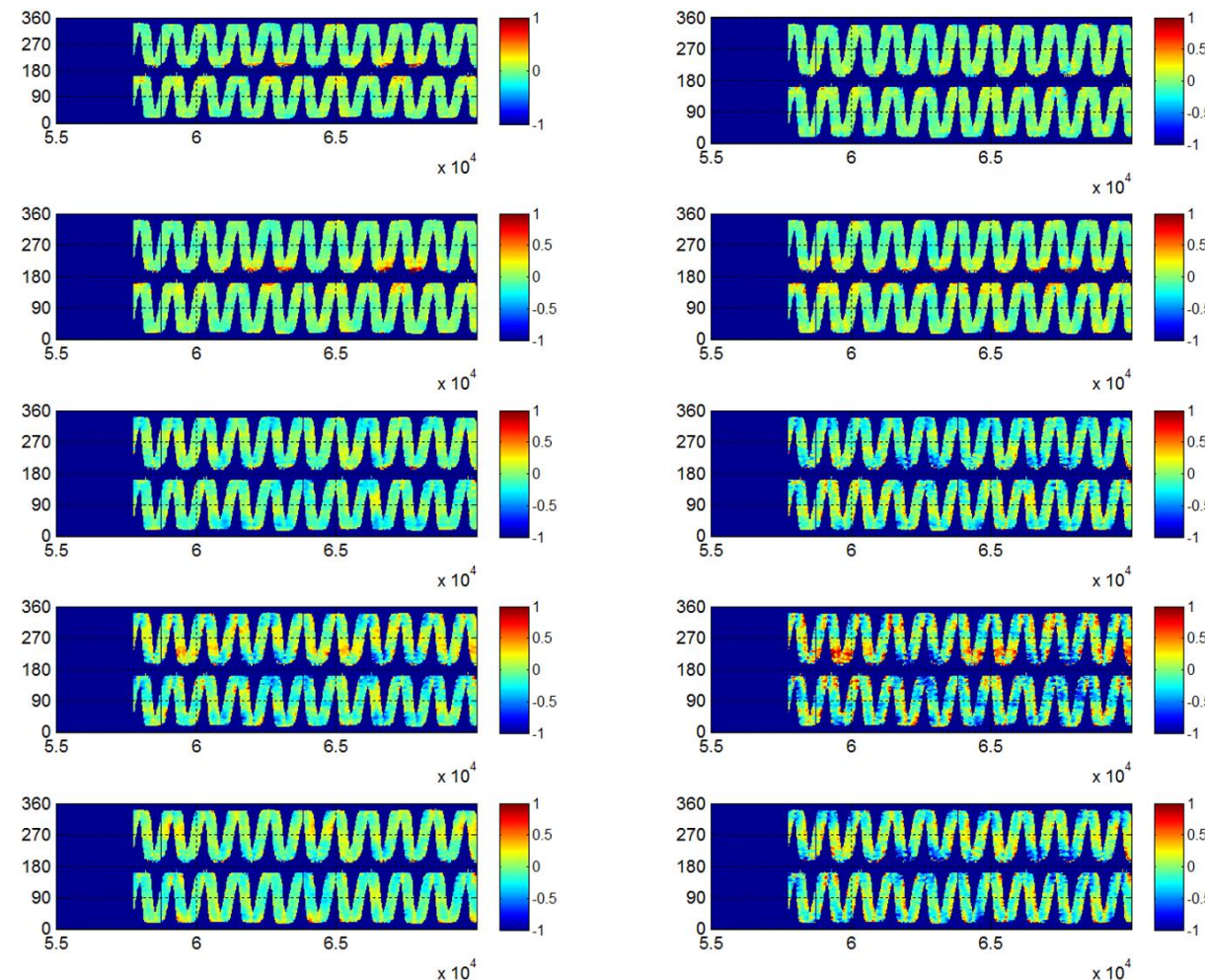
The RSS Calibration and Retrieval System





Radiometric Calibration

- Primary Method is comparison to GMI.
 - GMI is absolutely calibrated (Wentz and Draper, 2016)
 - GMI radiances converted to COWVR radiances using a RTM over the oceans.
 - Receiver linearity can be investigated by adding comparisons over the Amazon rainforest.
- Needs to be monitored over entire mission to guard against drifts.





Wind Algorithm

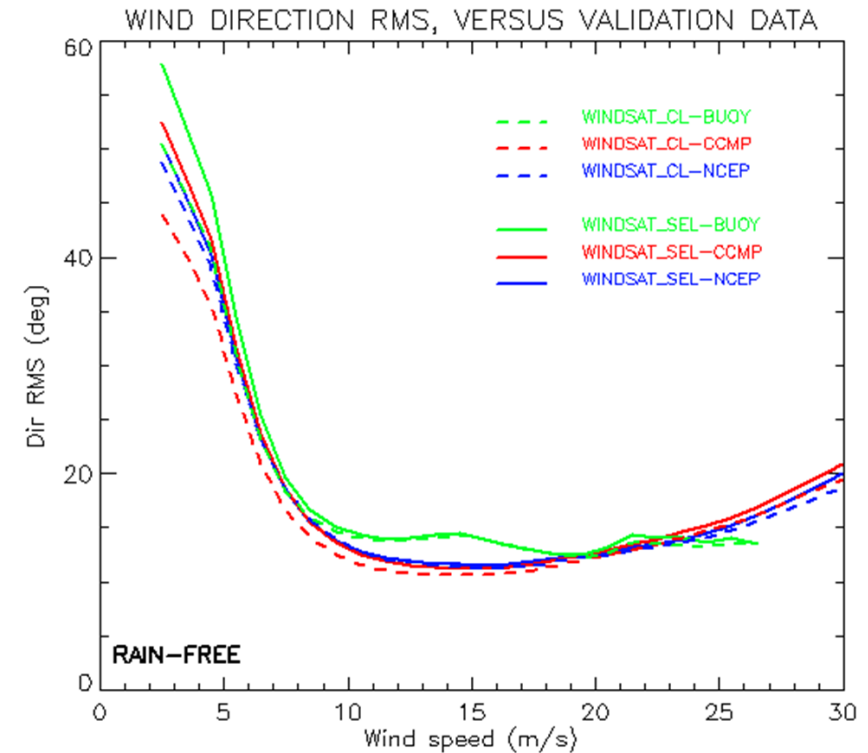
- Adapt our WindSat Algorithm to COWVR
 - Changes include
 - Lack of low frequency channels
 - De-rotating polarizations due to rotating antenna
 - “back look” available for all swath positions – should lead to good direction retrievals
 - Simplified footprint geometry – only one feed horn!
 - Step 1 – Find wind speed using a multistep regression algorithm (The regression is trained using the simulated data)
 - Step 2 – Find direction ambiguities by minimizing sum-of-squares for all channels
 - Step 3– Choose direction ambiguity using median filter method
 - (these are all proven methods for multi-look radiometers)

Wind Validation

- Compare to:

- Buoys
- NWP output
- CCMP

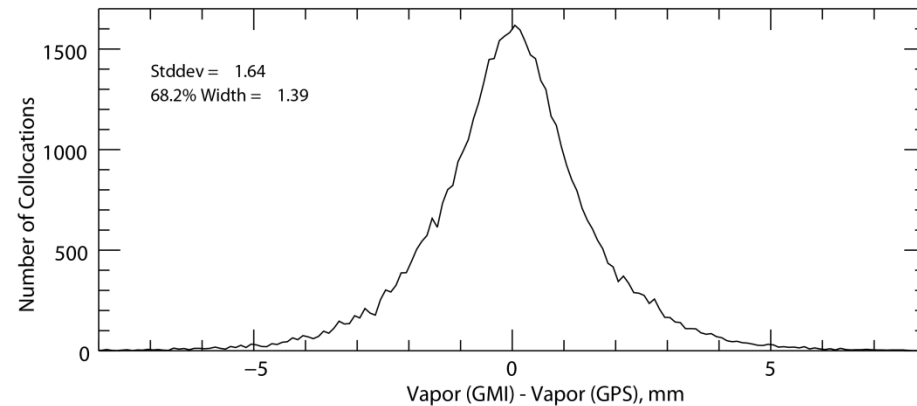
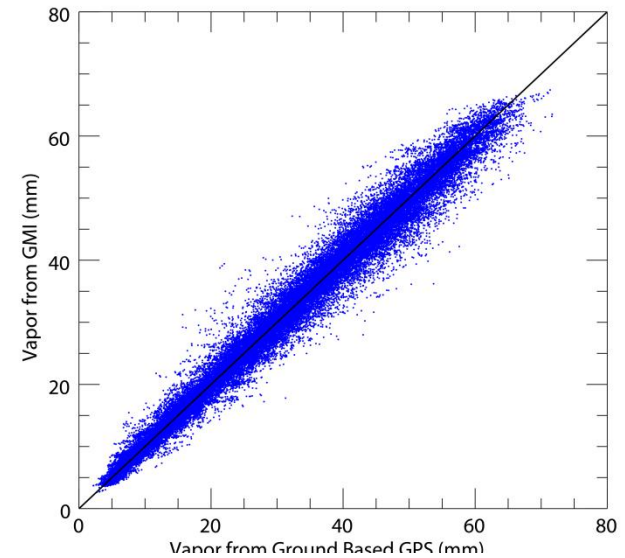
Using binned wind speed differences, binned direction differences, Ebuchi plots, overall means and std. devs.



Vapor, Clouds and Rain

- These are retrieved simultaneously with wind speed by the multistep regression algorithm.
- Vapor can be validated via comparison with ground-based GPS results from small islands.

Example from GMI





Conclusions

- We are excited about COWVR
 - It could be a (relatively) low cost way to get ocean vector winds in the future (especially if future COWVR's include 11 GHz).
 - Low-cost satellites could make it possible to have more satellites operating at same time – better coverage, better assimilation into NWP, possible to study diurnal variability.
 - Two-look capability should produce good direction retrievals than “classic” WindSat products.